

# ECONOMETRICS





NEW

SZÉCHENYI PLAN

# ECONOMETRICS

Sponsored by a Grant TÁMOP-4.1.2-08/2/A/KMR-2009-0041

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The project is supported  
by the European Union.

National Development Agency  
[www.ujszecsenyiterv.gov.hu](http://www.ujszecsenyiterv.gov.hu)  
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The projects have been supported  
by the European Union.

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# ECONOMETRICS

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June 2010

# ECONOMETRICS

Week 12.

Time series regressions I

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# Plan

Regression on stationary time series

Consequences of autocorrelated error terms

Testing autocorrelation

Handling autocorrelation

Textbook: M 6.1–6.5., 6.8.

# Reminder: cross sectional regression with stochastic regressors

Fixed regressors are less sensible in case of time series

Model with stochastic variables:  $y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_k x_{ik} + u_i$

Conditions for unbiasedness of OLS

$(y_i, x_{i1}, x_{i2}, \dots, x_{ik})$  ( $i = 1, \dots, n$ ) random sample of the model

$E(u | x_1, x_2, \dots, x_k) = 0$

No perfect collinearity

If homoscedasticity is also assumed, the following statements are true

The usual formula of variance is valid, the OLS estimator is asymptotically normal

OLS is BLUE.

If normality of error term is also assumed then small sample tests (t-test, F-test) are also valid.

# Regression with stationary variables

$$y_t = \beta_0 + \beta_1 x_{t1} + \beta_2 x_{t2} + \dots + \beta_k x_{tk} + u_t$$

If  $x_{ti}$  ( $i = 1, \dots, k$ ) and  $y_t$  are stationary then sufficient conditions for consistency of OLS:

$$E(u_t | x_{t1}, x_{t2}, \dots, x_{tk}) = 0 \text{ and}$$

No perfect collinearity

Further assumptions are needed for asymptotic validity of the usual tests (validity of formulas of variance etc.):

Homoscedasticity and

No autocorrelation in the error terms:

$$E(u_t u_s | x_{t1}, \dots, x_{tk}, x_{s1}, \dots, x_{sk}) = 0 \text{ (} t \neq s \text{)}$$



# Regression with stationary variables (cont.)

The same is true in case of trend stationarity, but trend has to be included as regressor

Some  $x_{ti}$  might be lagged  $y_t$  (but the exogeneity condition has to hold!)

E.g. stationary AR(1) model:  $k = 1$ ,  $x_{t1} = y_{t-1}$

OLS estimation of the coefficient is consistent, asymptotically normal (but not unbiased!)

# Autocorrelation of the error terms in the stationary regression

If the error terms are autocorrelated in a stationary regression then

OLS is still consistent,

But not BLUE,

And the common formula of variance and the usual tests are not valid!

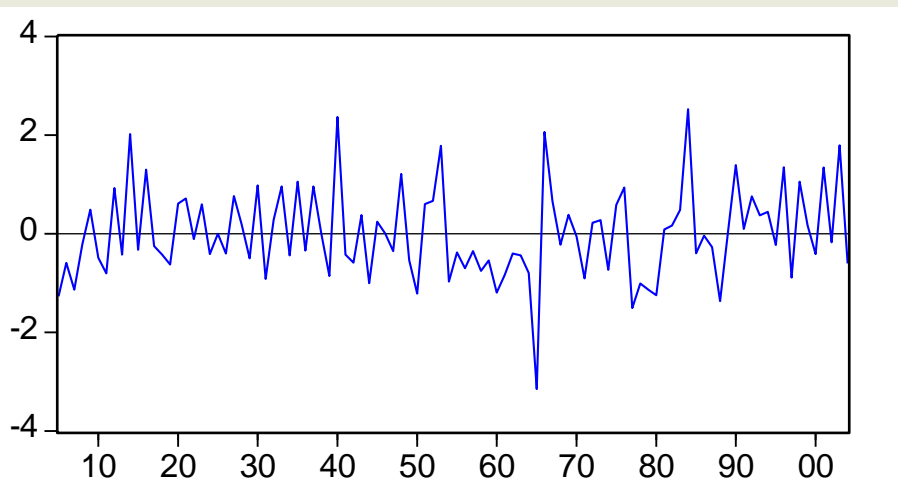
Size of bias in variance:  
M page 285–286.

# Testing autocorrelation of error terms

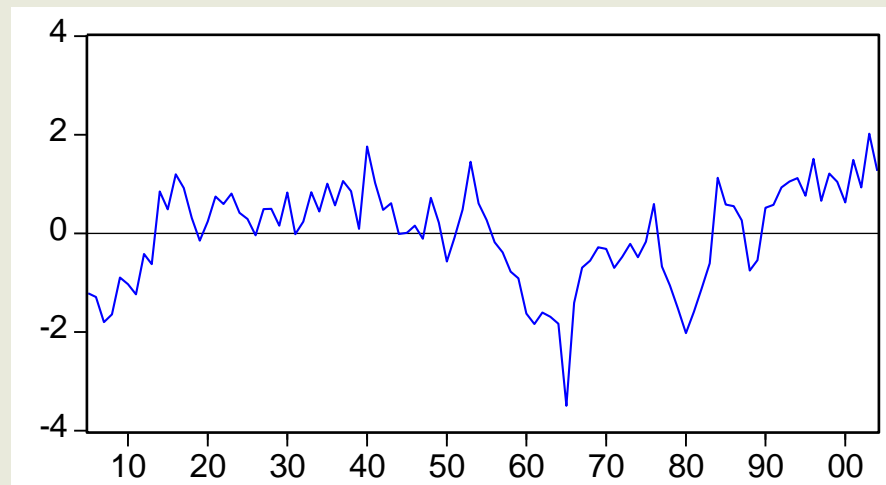
Durbin–Watson-test

Breusch–Godfrey-test

white noise error term



autocorrelated error term



# Durbin–Watson-test

Analyzes the residuals of OLS regression:

$$d = \frac{\sum_{t=2}^n (\hat{u}_t - \hat{u}_{t-1})^2}{\sum_{t=1}^n \hat{u}_t^2} = \frac{\sum_{t=2}^n \hat{u}_t^2 - 2 \sum_{t=2}^n \hat{u}_t \hat{u}_{t-1} + \sum_{t=2}^n \hat{u}_{t-1}^2}{\sum_{t=1}^n \hat{u}_t^2} \approx 2 - 2 \frac{\sum_{t=2}^n \hat{u}_t \hat{u}_{t-1}}{\sum_{t=1}^n \hat{u}_t^2}$$

Estimator of first order autocorrelation:

$$\hat{\rho} = \frac{\sum_{t=2}^n \hat{u}_t \hat{u}_{t-1}}{\sum_{t=1}^n \hat{u}_t^2}$$

$$d \approx 2(1 - \hat{\rho})$$

$$0 \leq d \leq 4 \quad (-1 \leq \rho \leq 1)$$

$$d = 2 \quad \Leftrightarrow \quad \rho = 0 \text{ (white noise)}$$

$$0 < d < 2 \quad \Leftrightarrow \quad \rho > 0 \text{ (positive autocorrelation)}$$

$$2 < d < 4 \quad \Leftrightarrow \quad \rho < 0 \text{ (negative autocorrelation)}$$

# DW-test, cont.

$H_0: \rho = 0$ ,  $H_1: \rho > 0$  (one sided test!)

The test has two critical values because the distribution of the test statistic depends on the regressors:  $d_L$  (lower value),  $d_U$  (upper value)

Decision rule:

Accept  $H_0$  if  $d > d_U$

Reject  $H_0$  if  $d < d_L$

Cannot decide if  $d_L < d < d_U$  (neutral, grey zone)

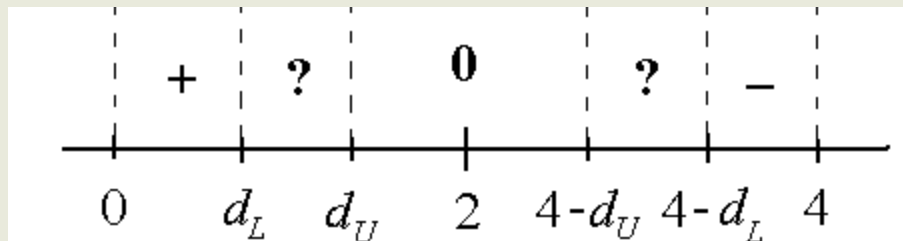
Testing negative autocorrelation:

Use  $4 - d$  instead of  $d$ , otherwise everything is the same

Accept  $H_0$  if  $4 - d > d_U$

Reject  $H_0$  if  $4 - d < d_L$

Cannot decide if  $d_L < 4 - d < d_U$  (neutral, grey zone)



# Limitations of DW-test

Can be used only for AR(1) residuals

In some cases ( $d_L < d < d_U$ ) the test is not conclusive

Cannot be used for distributed lag models  
(in some cases, see later)

# Breusch–Godfrey-test

AR( $p$ ) model of error terms:

$$u_t = \rho_1 u_{t-1} + \rho_2 u_{t-2} + \dots + \rho_p u_{t-p} + e_t$$

$$H_0: \rho_1 = \rho_2 = \dots = \rho_p = 0$$

Regress the estimated error term on the explanatory variables and  $p$  lags of the error term

Under  $H_0$ , asymptotically  $nR^2 \sim \chi_p^2$

# Handling autocorrelation

Adjusting the standard error of OLS estimation: Newey-West

Just as the White-procedure adjusts the standard error of OLS in case of heteroscedasticity

Generalized Least Squares (GLS) types of estimations, e.g. Cochrane-Orcutt procedure



# Cochrane–Orcutt-procedure

## Model

$$y_t = \beta_0 + \beta_1 x_{1t} + \beta_2 x_{2t} + \dots + \beta_k x_{kt} + u_t$$

$$u_t = \rho u_{t-1} + e_t, e_t \sim \text{IN}$$

## Quasi differencing

$$(y_t - \rho y_{t-1}) = (1 - \rho)\beta_0 + \beta_1(x_{1t} - \rho x_{1,t-1}) + \dots + \beta_k(x_{kt} - \rho x_{k,t-1}) + e_t$$

Regress  $y_t - \rho y_{t-1}$  on  $x_{it} - \rho x_{i,t-1}$  variables

## Procedure

OLS estimation, then estimation of  $\rho$  based on the residuals

OLS of the quasi-differenced time series

Iteration can also be used (does not improve asymptotically the efficiency)

Since  $\rho$  is estimated, if  $\rho$  is close to 0 then not necessarily better than OLS

# Example: estimation of static Phillips-curve (USA) with OLS

## Considerable autocorrelation

Dependent Variable: INF  
Method: Least Squares  
Date: 02/24/09 Time: 12:23  
Sample: 1948 2003  
Included observations: 56

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	1.053565	1.547957	0.680617	0.4990
UNEM	0.502378	0.265562	1.891752	0.0639
R-squared	0.062154	Mean dependent var	3.883929	
Adjusted R-squared	0.044786	S.D. dependent var	3.040381	
S.E. of regression	2.971518	Akaike info criterion	5.051084	
Sum squared resid	476.8157	Schwarz criterion	5.123418	
Log likelihood	-139.4304	Hannan-Quinn criter.	5.079128	
F-statistic	3.578726	Durbin-Watson stat	0.801482	
Prob(F-statistic)	0.063892			

Breusch-Godfrey Serial Correlation LM Test:

F-statistic	31.52897	Prob. F(1,53)	0.0000
Obs*R-squared	20.88778	Prob. Chi-Square(1)	0.0000

Test Equation:

Dependent Variable: RESID  
Method: Least Squares  
Date: 02/24/09 Time: 12:26  
Sample: 1948 2003  
Included observations: 56

Presample missing value lagged residuals set to zero.

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	2.555356	1.318280	1.938402	0.0579
UNEM	-0.457243	0.227341	-2.011267	0.0494
RESID(-1)	0.656330	0.116887	5.615066	0.0000

R-squared	0.372996	Mean dependent var	5.43E-16
Adjusted R-squared	0.349335	S.D. dependent var	2.944380
S.E. of regression	2.375048	Akaike info criterion	4.619996
Sum squared resid	298.9653	Schwarz criterion	4.728497
Log likelihood	-126.3599	Hannan-Quinn criter.	4.662061
F-statistic	15.76448	Durbin-Watson stat	1.808715
Prob(F-statistic)	0.000004		

# Example, cont.: correcting autocorrelation

Strong autocorrelation, the regression is basically on the differences! These estimates are more reliable.

Dependent Variable: INF  
 Method: Least Squares  
 Date: 02/24/09 Time: 13:20  
 Sample (adjusted): 1949 2003  
 Included observations: 55 after adjustments  
 Convergence achieved after 5 iterations

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	7.287078	2.287763	3.185242	0.0024
UNEM	-0.663959	0.330235	-2.010564	0.0496
AR(1)	0.782009	0.094683	8.259202	0.0000

R-squared	0.503681	Mean dependent var	3.807273
Adjusted R-squared	0.484592	S.D. dependent var	3.013295
S.E. of regression	2.163302	Akaike info criterion	4.434150
Sum squared resid	243.3536	Schwarz criterion	4.543641
Log likelihood	-118.9391	Hannan-Quinn criter.	4.476491
F-statistic	26.38569	Durbin-Watson stat	1.600203
Prob(F-statistic)	0.000000		

Inverted AR Roots	.78
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## Breusch-Godfrey Serial Correlation LM Test:

F-statistic	0.734056	Prob. F(1,51)	0.3956
Obs*R-squared	0.780397	Prob. Chi-Square(1)	0.3770

Test Equation:  
 Dependent Variable: RESID  
 Method: Least Squares  
 Date: 02/24/09 Time: 13:21  
 Sample: 1949 2003  
 Included observations: 55  
 Presample missing value lagged residuals set to zero.

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.198041	2.305251	0.085908	0.9319
UNEM	-0.017397	0.331705	-0.052446	0.9584
AR(1)	-0.055103	0.114662	-0.480565	0.6329
RESID(-1)	0.151531	0.176863	0.856771	0.3956

R-squared	0.014189	Mean dependent var	-1.33E-12
Adjusted R-squared	-0.043800	S.D. dependent var	2.122863
S.E. of regression	2.168855	Akaike info criterion	4.456223
Sum squared resid	239.9006	Schwarz criterion	4.602211
Log likelihood	-118.5461	Hannan-Quinn criter.	4.512678
F-statistic	0.244685	Durbin-Watson stat	1.715550
Prob(F-statistic)	0.864729		

# Distributed lag models

**Model:**  $y_t = \alpha + \beta_0 x_t + \beta_1 x_{t-1} + \dots + \beta_k x_{t-k} + u_t$

$\beta_0$ : immediate effect of a unit shock in  $x$  on  $y$

$\beta_0, \beta_1, \beta_2, \dots$ : lag distribution

$\beta_0 + \beta_1 + \dots + \beta_k$ : effect of a permanent unit shock in  $x$  on  $y$  (long run multiplier)

There are models with infinite lags, e.g. geometric lags (geometrically declining  $\beta$ -s)

# Seminar

## Time series regressions I

## AR(2)-process:

Stationarity, necessary conditions of stationarity

Solution of Yule–Walker equation

## Autocorrelations of ARMA(1,1) process

## Simulation of ARMA and ARIMA processes

## Comparison and simulation difference and trend stationary processes

## Box–Jenkins modelling, forecasting from ARIMA model

Example: modelling time series of (seasonally adjusted) industrial production